

Planting and MCMC Sampling from the Potts model

STACS 2025

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March 10, 2026

Potts Model

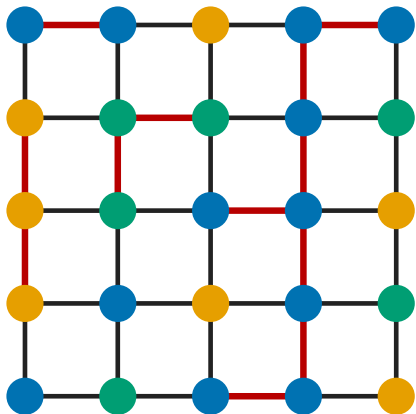
For a graph $G = (V, E)$ consider the set of q -colourings

$$\Omega = \{V \rightarrow [q]\}$$

Probability of a colouring $\sigma \sim e^{-\beta m(\sigma)}$

Inverse temperature parameter

monochromatic edges under σ



This 3-colouring has $m(\sigma) = 12$ monochromatic edges

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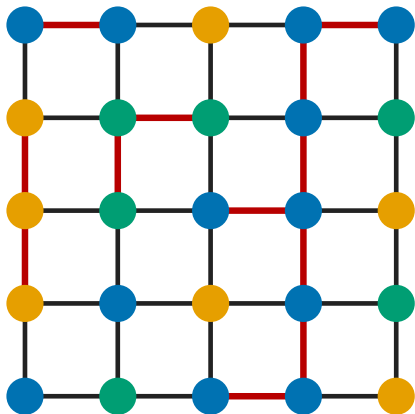
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(Approximate) Sampling from the Potts model

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A randomised algorithm with output distribution is (close to) π_G

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What about a “typical graphs”?

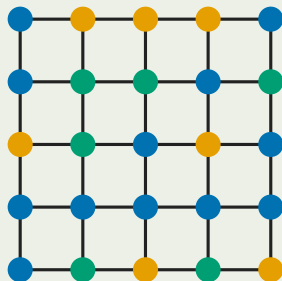
Random Cluster model

Markov chain-based algorithms working for all $\beta > 0$ on random regular graphs using representation via *random cluster model*

Random cluster model (RCM)

A distribution on *edge subsets*

Potts \rightarrow *RCM*: keep each edge with probability $1 - e^{-\beta}$



Idea: obtain a RCM sample. Colour components to get a Potts sample

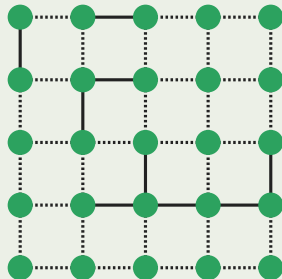
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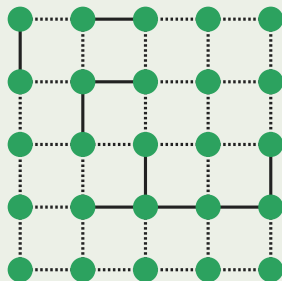
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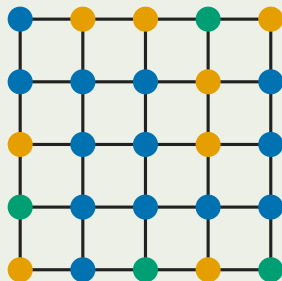
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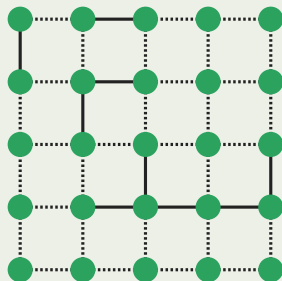
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Probability of $F \subseteq E \sim$

$$q^{c(F)} (e^{\beta} - 1)^{|F|}$$

Number of components in (V, F)



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Glauber dynamics

States: $\Omega_G = \{F \subseteq E\}$

Transition $X_t \rightarrow X_{t+1}$:

- 1 Pick a uniformly random edge $e \in E$
- 2 If e is a *cut-edge* in $X_t \cup \{e\}$ then
 - 1 With probability $\frac{1-e^{-\beta}}{1+e^{-\beta}(q-1)}$ set $X_{t+1} := X_t \cup \{e\}$
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Sampling from RCM on random regular graphs

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Converges to the RC distribution

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Converges to the RC distribution

How fast?

How many steps suffice for convergence?

- Blanca, Gheissari (2020): $O(n \log n)$ steps for low β and any q from any X_0
- Blanca, Gheissari (2023): $O(n^{1+o(1)})$ steps for high β and any q from any X_0
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Bottleneck between two typical sample types: worst-case exponential convergence for a window of β 's

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Bottleneck between two typical sample types: worst-case exponential convergence for a window of β 's

Can we extend the last result to all q ?

Theorem (Galani, Goldberg, S)

Let $d, q \geq 3$ and $\beta > 0$. Then with high probability for a random d -regular graph G :

- If $\beta < \beta_c$ then the Glauber dynamics with $X_0 := \emptyset$ converges in $O(n \log n)$ steps.
- If $\beta > \beta_c$ and $q \geq (5d)^5$, then the Glauber dynamics with $X_0 := E$ converges in $O(n \log n)$ steps.

Where β_c is a critical temperature where a typical sample changes from disordered (few edges in, colour proportions are roughly equal) to ordered (most of edges in, most of vertices have one colour)

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We modify the proof techniques for high- q using a first-order method known as *planting*

Phases of the Potts model

Key part of the proof: *typical configuration* does not differ “too much” from χ_t

Phases of the Potts model

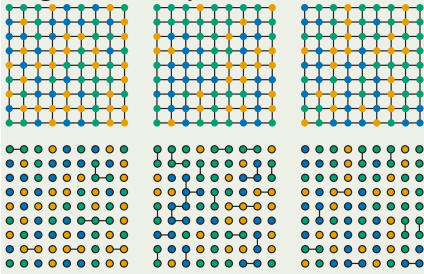
Key part of the proof: *typical configuration* does not differ “too much” from X_t

What is a *typical configuration*?

Disordered Phase ($\beta < \beta_c$)

Potts: all colours of roughly equal proportions

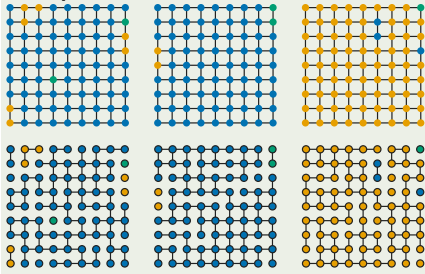
RCM: at most a small fraction of edges in a sample



Ordered Phase ($\beta > \beta_c$)

Potts: one dominant colour, the rest with \approx equal proportions

RCM: vast majority of edges in a sample



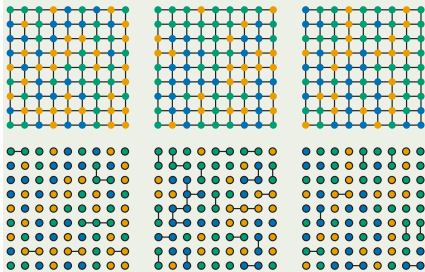
Planting of the Potts model

Disordered Phase ($\beta < \beta_c$)

Colours are symmetrical

$$\# \textcircled{i} : \frac{n}{q} + o(n)$$

$$\# \textcircled{i} - \textcircled{j} \sim e^{\beta \cdot \mathbb{1}\{i=j\}}$$

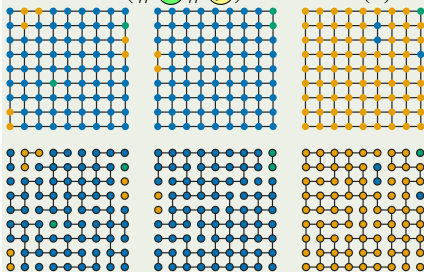


Ordered Phase ($\beta > \beta_c$)

Pick a u.a.r. dominant colour c

$$\# \textcircled{i} \sim \frac{1-a}{q} + o(1) \quad \# \textcircled{c} \sim a + o(1)$$

$$\# \textcircled{i} - \textcircled{j} \sim e^{\beta \cdot \mathbb{1}\{i=j\}} (\# \textcircled{i} \# \textcircled{j})^{(d-1)/d} + o(1)$$



Planting of the Potts model

Planting: we can generate a random graph and random sample at the same time

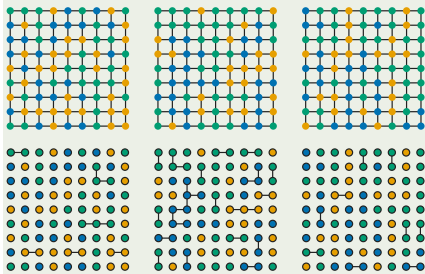
With high probability: (random graph, Potts sample) \sim u.a.r. coloured graph with a given vertex and edge colour statistics

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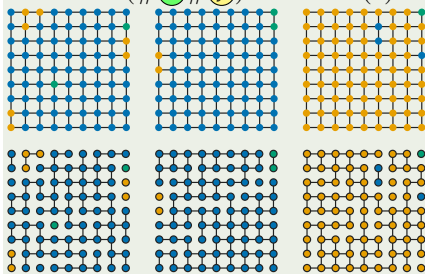


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Key proof ingredient ($\beta < \beta_c$)

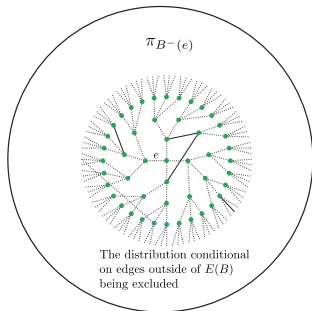
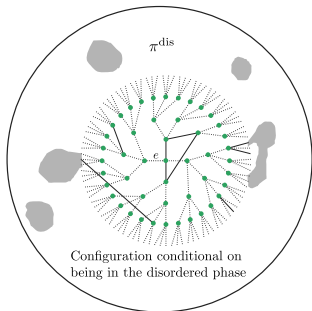
Weak Spatial Mixing within the disordered phase

Key proof ingredient: for every edge e show

$$| \pi^{\text{dis}}(e \in \cdot) - \pi_{B^-(e)}(e \in \cdot) | = O\left(\frac{1}{n}\right)$$

RC distribution
conditional on being in
the disordered phase

RC distribution on $\approx \log n$ -radius
neighbourhood conditional
on outside edges being out



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Bound using first-order methods by analysing the planted random graph

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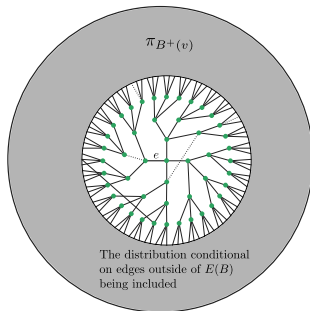
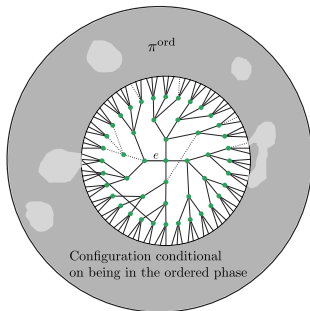
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This is at most the probability that some length $\approx \log n$ avoids the largest component of $(V, F \setminus \{e\})$

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Planting: with high probability, every length $\approx \log n$ path hits the giant

- $\tilde{O}(n)$ sampling algorithm for Potts on random regular graphs for almost all parameter ranges
 - Can we improve q from $(5d)^5$ to 3?
The bottleneck is in the size of the largest component of the typical RCM sample
 - Can we obtain algorithm for β_c ?
We need to be able to estimate the proportions of the phases
- Can we extend planting to random *average* bounded degree graphs?
 - Approach for random regular graphs does not result in correct degree statistics for the ordered phase

I am looking for a postdoc!

Additional Slides

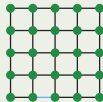
Proof Sketch ($p > p_c$)

$$|\pi_G(\cdot; q, p) - \chi_t|_{\text{TV}} \leq \underbrace{|\pi_G(\cdot; q, p) - \pi^{\text{ord}}|_{\text{TV}}}_{e^{-\Omega(n)}} + \underbrace{|\pi^{\text{ord}} - \chi_t|_{\text{TV}}}_{\text{Goal: show } \leq \frac{1}{5}}$$

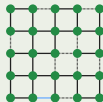
$\xrightarrow{\text{Glauber from all-in}} \quad \xrightarrow{\pi_G(\cdot | \cdot \text{ in ordered phase})}$

Two coupled copies of Glauber

χ_t : starting from all-in



$\hat{\chi}_t$: starting from π^{ord} ,
restricted to ordered phase



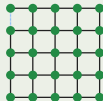
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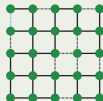
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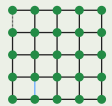
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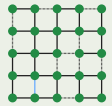
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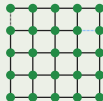
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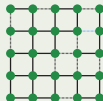
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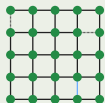
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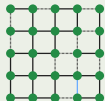
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$$|\chi_t - \hat{\chi}_t|_{\text{TV}} \leq \Pr(\hat{\chi}_t \neq \chi_t)$$

Union bound:

$$\leq \sum_{e \in E} \Pr(\chi_t, \hat{\chi}_t \text{ disagree on } e)$$

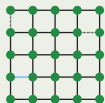
Proof Sketch ($p > p_c$)

$$|\pi_G(\cdot; q, p) - X_t|_{\text{TV}} \leq \underbrace{|\pi_G(\cdot; q, p) - \pi^{\text{ord}}|_{\text{TV}}}_{e^{-\Omega(n)}} + \underbrace{|\pi^{\text{ord}} - X_t|_{\text{TV}}}_{\text{Goal: show } \leq \frac{1}{5}}$$

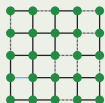
Glauber from all-in $\pi_G(\cdot | \cdot \text{ in ordered phase})$

Two coupled copies of Glauber

X_t : starting from all-in



\hat{X}_t : starting from π^{ord} ,
restricted to ordered phase



$$|X_t - \hat{X}_t|_{\text{TV}} \leq \Pr(\hat{X}_t \neq X_t)$$

Union bound:

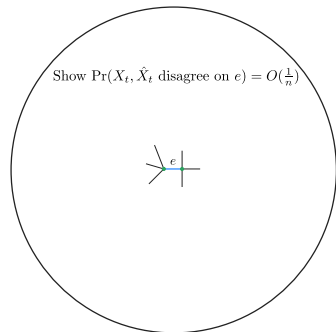
$$\leq \sum_{e \in E} \Pr(X_t, \hat{X}_t \text{ disagree on } e)$$

Monotonicity: As long as $(\hat{X}_t)_{t \leq T}$ has not ignored any updates: $\hat{X}_T \leq X_T$

Unlikely to happen in polynomially many steps

Proof sketch ($p > p_c$): edge marginals

Glauber restricted to the ordered phase, from π^{ord}

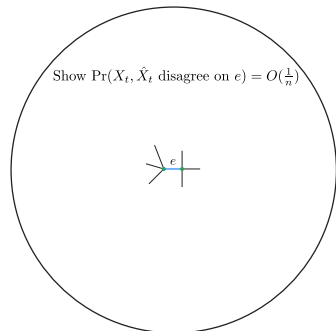


Goal: For any edge e , show that $\Pr(X_t, \hat{X}_t \text{ disagree on } e)$ is small enough

Glauber from all-in

Proof sketch ($p > p_c$): edge marginals

Glauber restricted to the ordered phase, from π^{ord}



Goal: For any edge e , show that $\Pr(X_t, \hat{X}_t \text{ disagree on } e)$ is small enough

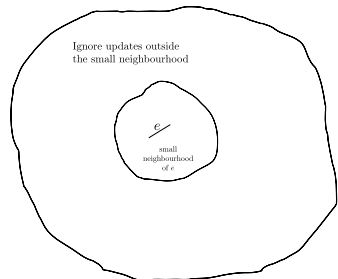
Glauber from all-in

Use *local behaviour* to extrapolate something *global*

Idea: can we show edges too far away have little influence on e ?

Proof sketch ($p > p_c$): edge marginals

Glauber restricted to the ordered phase, from π^{ord}



Goal: For any edge e , show that

$\Pr(X_t, \hat{X}_t \text{ disagree on } e)$ is small enough

Glauber from all-in

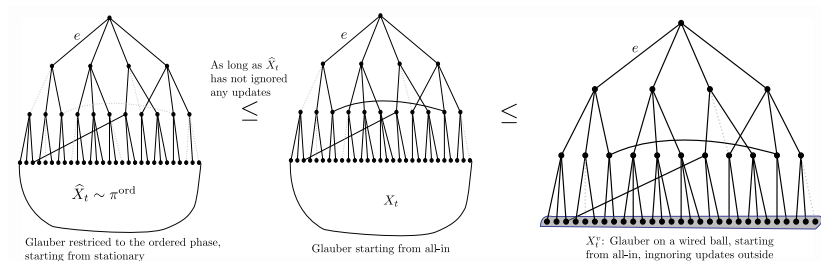
Use *local behaviour* to extrapolate something *global*

Idea: can we show edges too far away have little influence on e ?

Compare to an *intermediate distribution*: a chain restricted to a *neighbourhood* around e , starting from all-in

Proof sketch ($p > p_c$): edge marginals

Pick $v \in V$ incident to e , $r \sim \frac{\log n}{d}$: consider a restricted chain, X_t^v , ignoring updates outside a the radius- r ball around v , starting from all-in



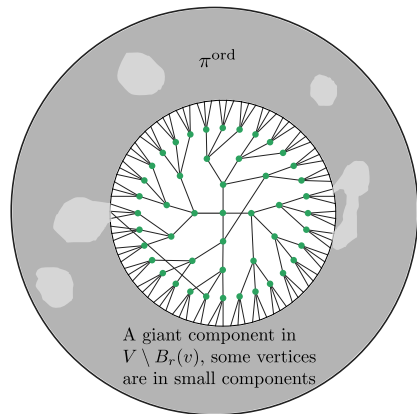
As long as \hat{X}_t has not ignored any updates that would take it outside the phase, $\hat{X}_t \leq X_t \leq X_t^v$

Proof sketch ($p > p_c$): edge marginals

Conditioned on \hat{X}_T having not ignored any updates, probability that X_T and \hat{X}_T disagree on e is at most

$$\begin{aligned}
 & \left| \Pr(e \in X_T^v \mid \hat{X}_T \text{ ignored no updates}) - \Pr(e \in \hat{X}_T \mid \hat{X}_T \text{ ignored no updates}) \right| \\
 & \quad \begin{array}{c} \text{Glauber on the wired ball} \\ \downarrow \\ \text{Glauber restricted to the ordered phase} \end{array} \\
 & \leq C \cdot \Pr(\hat{X}_T \text{ ignored no updates}) + \left| \Pr(e \in X_T^v) - \Pr(e \in \hat{X}_T) \right| \\
 & \quad \underbrace{\hspace{10em}}_{\text{unlikely for } T \text{ a polynomial}} \\
 & \leq C \cdot \Pr(\hat{X}_T \text{ ignored no updates}) \\
 & + \underbrace{\left| \Pr(e \in X_T^v) - \pi_{B^+(v)}(e \in \cdot) \right|}_{\text{Local mixing on tree-like neighbourhoods}} + \underbrace{\left| \underbrace{\pi_{B^+(v)}(e \in \cdot)}_{\text{RC on the wired ball}} - \underbrace{\Pr(e \in \hat{X}_T)}_{\pi^{\text{ord}}(e \in \cdot)} \right|}_{\text{Weak spatial mixing within the ordered phase}}
 \end{aligned}$$

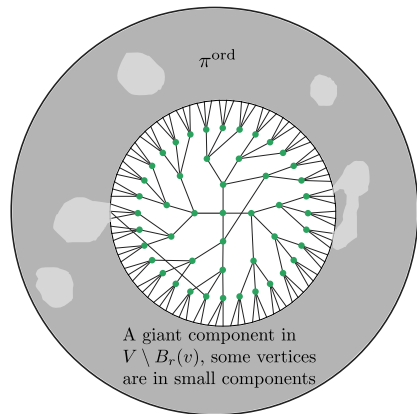
WSM within the ordered phase



If all vertices of $\partial B_r(v)$ are in the giant component, we are done

Otherwise, we need to reveal further

WSM within the ordered phase

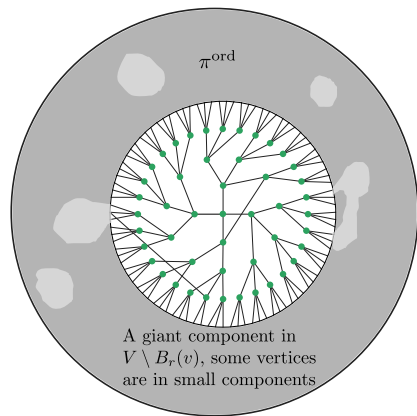


If all vertices of $\partial B_r(v)$ are in the giant component, we are done

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Question: what is a phenomenon that causes us to reveal further? How to characterize the event “we reveal e before getting connected boundary”?

WSM within the ordered phase



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Otherwise, we need to reveal further

Question: what is a phenomenon that causes us to reveal further? How to characterize the event “we reveal e before getting connected boundary”?

Answer: long path avoiding the giant of $(V, F \setminus \{e\})$