

Approximating $\ell_{q \rightarrow p}$ Norms of Non-Negative Matrices in Nearly-Linear Time

Etienne Objois, Adrian Vladu

Institut de Recherche en Informatique Fondamentale (IRIF)

March 10, 2026



Spectral Norm

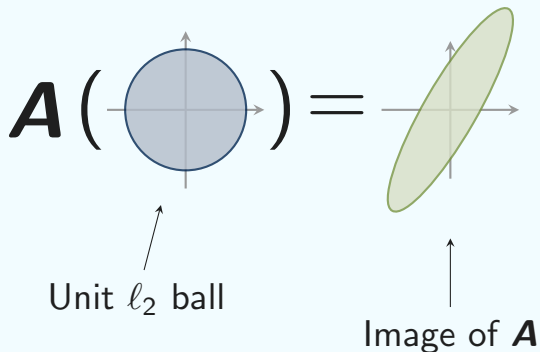
Spectral Norm

We want to approximate

$$\|\mathbf{A}\|_2 = \max_{\mathbf{x}: \|\mathbf{x}\|_2 \leq 1} \|\mathbf{Ax}\|_2 = \max_{\mathbf{x} \neq \mathbf{0}} \frac{\|\mathbf{Ax}\|_2}{\|\mathbf{x}\|_2}.$$

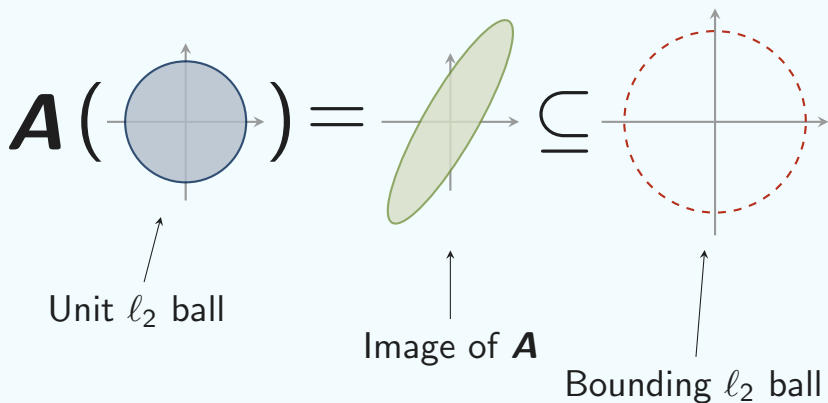
Size of a Matrix

What is the “size” of a matrix \mathbf{A} ?



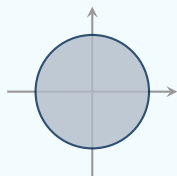
Size of a Matrix

What is the “size” of a matrix \mathbf{A} ?



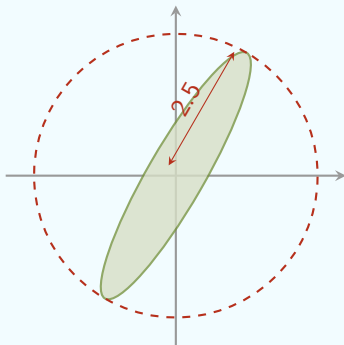
Spectral Norm: Visual Representation

Unit ℓ_2 ball



$$\rightarrow \mathbf{A} = \begin{pmatrix} 1.3 & -1.2 \\ 2.2 & 0.8 \end{pmatrix} \rightarrow$$

Image of \mathbf{A}



$$\max \|\mathbf{Ax}\|_2 = 2.5$$

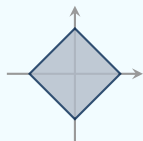
Other Unit Balls

$$\|\mathbf{x}\|_p = (\sum_i |\mathbf{x}_i|^p)^{\frac{1}{p}}$$

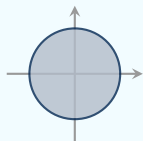
$p = 2$: euclidean norm

$p \geq 1$: norm

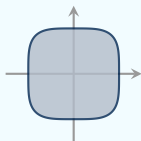
Unit ℓ_1 ball
 $\{\|\mathbf{x}\|_1 \leq 1\}$



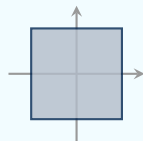
Unit ℓ_2 ball
 $\{\|\mathbf{x}\|_2 \leq 1\}$



Unit ℓ_4 ball
 $\{\|\mathbf{x}\|_4 \leq 1\}$

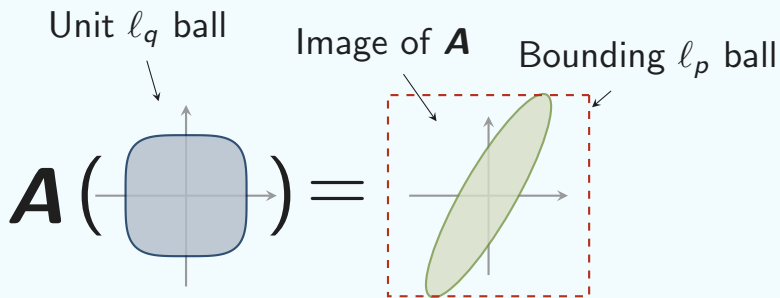


Unit ℓ_∞ ball
 $\{\|\mathbf{x}\|_\infty \leq 1\}$



Generalizing to $\ell_{q \rightarrow p}$ Spaces

$$\|\mathbf{A}\|_{q \rightarrow p} = \max_{\mathbf{x}} \frac{\|\mathbf{Ax}\|_p}{\|\mathbf{x}\|_q}$$



General Version of our Problem

For $q, p \geq 1$, and a matrix \mathbf{A} , find

$$\|\mathbf{A}\|_{q \rightarrow p} = \max_{\|\mathbf{x}\|_q=1} \|\mathbf{Ax}\|_p.$$

General Version of our Problem

For $q, p \geq 1$, and a matrix \mathbf{A} , find

$$\|\mathbf{A}\|_{q \rightarrow p} = \max_{\|\mathbf{x}\|_q=1} \|\mathbf{Ax}\|_p.$$

- MaxCut: $\|\mathbf{A}\|_{\infty \rightarrow 1}$.

General Version of our Problem

For $q, p \geq 1$, and a matrix \mathbf{A} , find

$$\|\mathbf{A}\|_{q \rightarrow p} = \max_{\|\mathbf{x}\|_q=1} \|\mathbf{Ax}\|_p.$$

- MaxCut: $\|\mathbf{A}\|_{\infty \rightarrow 1}$.
 - Small-Set Expansion Hypothesis (a variation of Unique Game Conjecture).
- \implies the problem is **hard** under some conjectures.

Our Motivation and Assumptions

Linear Oblivious Routings

- **For a routing matrix \mathbf{A} :**
 - $\|\mathbf{A}\|_p$ is the **quality** of the routing.
 - **Goal:** Compute high quality \mathbf{A} .
 - **Certificate:** Compute the quality of the routing.

Our Problem

For $q = p \geq 1$, an entry wise non-negative matrix \mathbf{A} , and $\varepsilon > 0$ find $\mathbf{x} \in \mathbb{R}_{\geq 0}^n$ such that

$$\frac{\|\mathbf{Ax}\|_p}{\|\mathbf{x}\|_p} \geq (1 - \varepsilon) \cdot \|\mathbf{A}\|_p.$$

Our Motivation and Assumptions

Linear Oblivious Routings

- **For a routing matrix \mathbf{A} :**
 - $\|\mathbf{A}\|_p$ is the **quality** of the routing.
 - **Goal:** Compute high quality \mathbf{A} .
 - **Certificate:** Compute the quality of the routing.
- **Properties of a routing matrix:**
 - 1 \mathbf{A} is entry wise non-negative.
 - 2 $q = p$.

Our Problem

For $q = p \geq 1$, an entry wise non-negative matrix \mathbf{A} , and $\varepsilon > 0$ find $\mathbf{x} \in \mathbb{R}_{\geq 0}^n$ such that

$$\frac{\|\mathbf{Ax}\|_p}{\|\mathbf{x}\|_p} \geq (1 - \varepsilon) \cdot \|\mathbf{A}\|_p.$$

Potentials: Definition for the ℓ_2 Case

$$\mathbf{x}_{t+1} = \frac{\mathbf{A}^T \mathbf{A} \mathbf{x}_t}{\left\| \mathbf{A}^T \mathbf{A} \mathbf{x}_t \right\|_2}, \quad \Phi(\mathbf{x}_t) = \frac{\mathbf{A}^T \mathbf{A} \mathbf{x}_t}{\mathbf{x}_t}$$

vector operations
are coordinate wise

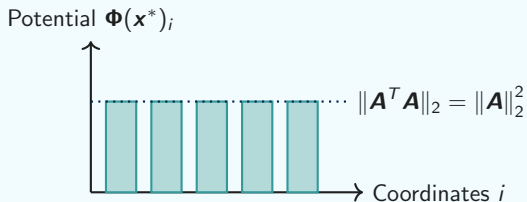
- Potential = a vector of \mathbf{x} .
- $\Phi(\mathbf{x}) \approx$ gradient + something.

Potentials: Definition for the ℓ_2 Case

$$\mathbf{x}_{t+1} = \frac{\mathbf{A}^T \mathbf{A} \mathbf{x}_t}{\|\mathbf{A}^T \mathbf{A} \mathbf{x}_t\|_2}, \quad \Phi(\mathbf{x}_t) = \frac{\mathbf{A}^T \mathbf{A} \mathbf{x}_t}{\mathbf{x}_t}$$

vector operations are coordinate wise

- Potential = a vector of \mathbf{x} .
- $\Phi(\mathbf{x}) \approx$ gradient + something.

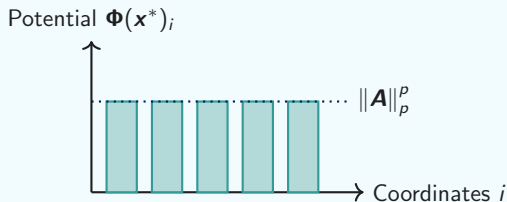


Potentials: Definition for the ℓ_p Case

$$\mathbf{x}_{t+1} = \frac{\mathbf{A}^T (\mathbf{A}\mathbf{x}_t)^{p-1}}{\left\| \mathbf{A}^T (\mathbf{A}\mathbf{x}_t)^{p-1} \right\|_p}, \quad \Phi(\mathbf{x}_t) = \frac{\mathbf{A}^T (\mathbf{A}\mathbf{x}_t)^{p-1}}{\mathbf{x}_t^{p-1}}$$

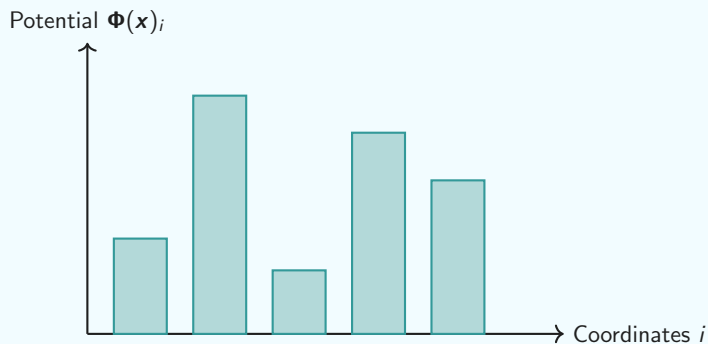
vector operations
are coordinate wise

- Potential = a vector of \mathbf{x} .
- $\Phi(\mathbf{x}) \approx$ gradient + something.



Potential Vector: Properties

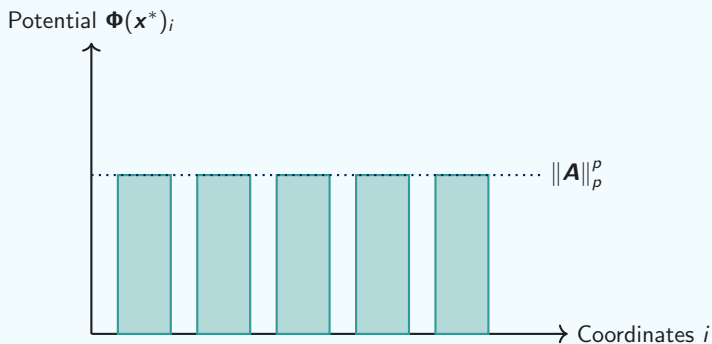
Three Properties:



Potential Vector: Properties

Three Properties:

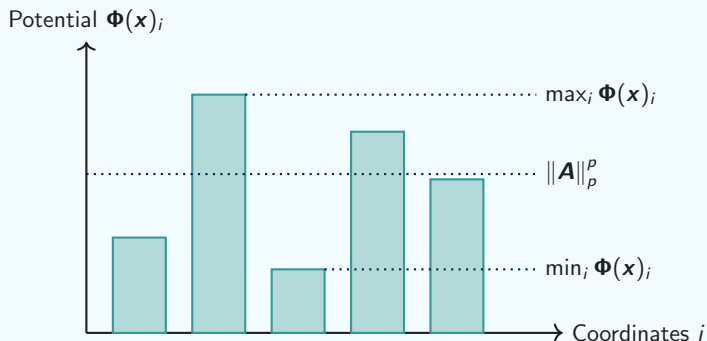
- 1 At optimum, $\Phi(\mathbf{x}^*)_i = \|\mathbf{A}\|_p^p$ for all i .



Potential Vector: Properties

Three Properties:

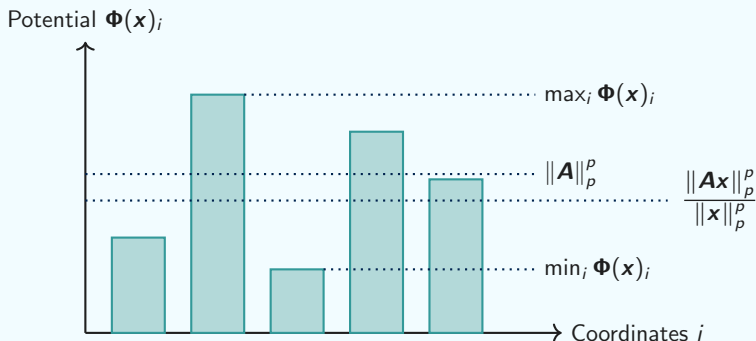
- 1 At optimum, $\Phi(\mathbf{x}^*)_i = \|\mathbf{A}\|_p^p$ for all i .
- 2 Entries of $\Phi(\mathbf{x})$ sandwich $\|\mathbf{A}\|_p^p$.



Potential Vector: Properties

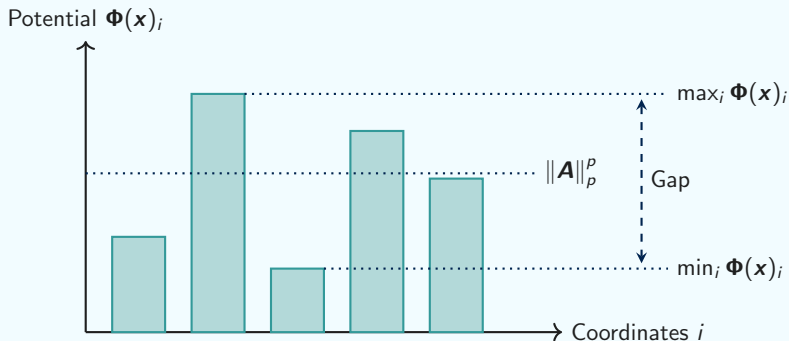
Three Properties:

- 1 At optimum, $\Phi(\mathbf{x}^*)_i = \|\mathbf{A}\|_p^p$ for all i .
- 2 Entries of $\Phi(\mathbf{x})$ sandwich $\|\mathbf{A}\|_p^p$.
- 3 Entries of $\Phi(\mathbf{x})$ sandwich $\|\mathbf{Ax}\|_p^p / \|\mathbf{x}\|_p^p$.



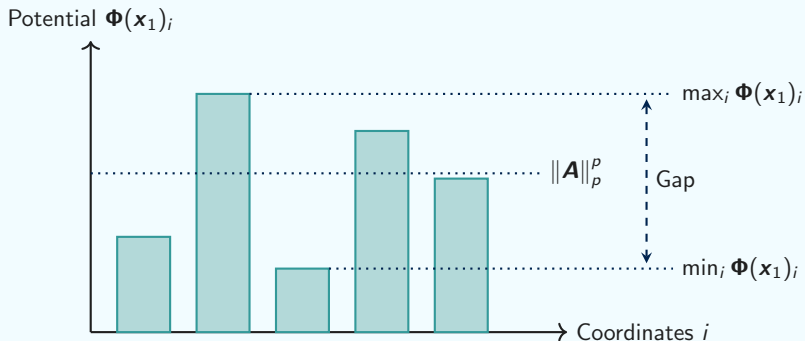
Visual Representation of Power Iteration

1 Goal: Find $\mathbf{x} \in \mathbb{R}_{>0}^n$ such that $\max_i \Phi(\mathbf{x})_i / \min_i \Phi(\mathbf{x})_i \leq 1 + \varepsilon$.



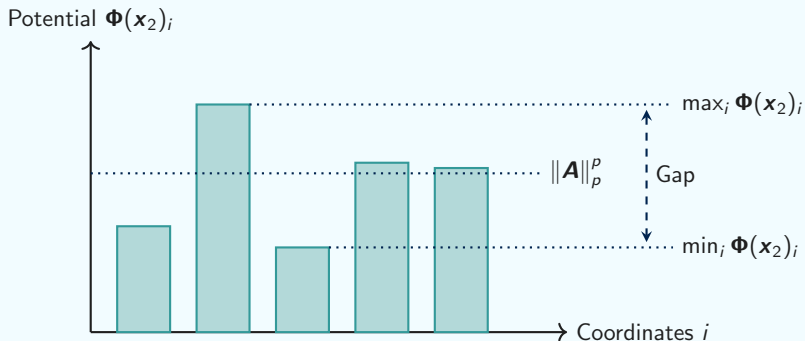
Visual Representation of Power Iteration

- 1 Goal:** Find $\mathbf{x} \in \mathbb{R}_{>0}^n$ such that $\max_i \Phi(\mathbf{x})_i / \min_i \Phi(\mathbf{x})_i \leq 1 + \varepsilon$.
- 2 [Boyd, '74]:** With Power Iteration, this ratio decreases.



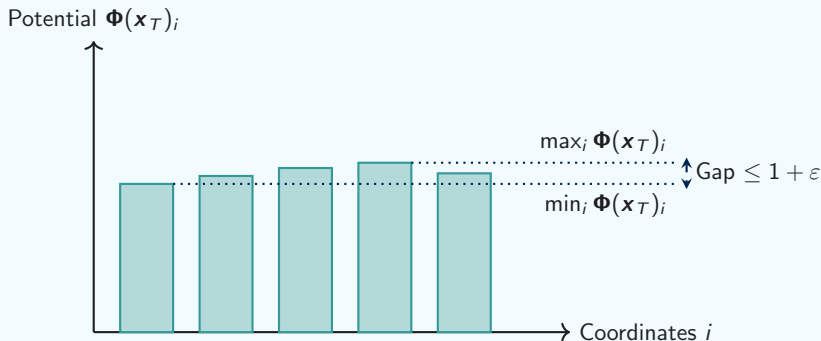
Visual Representation of Power Iteration

- 1 Goal:** Find $\mathbf{x} \in \mathbb{R}_{>0}^n$ such that $\max_i \Phi(\mathbf{x})_i / \min_i \Phi(\mathbf{x})_i \leq 1 + \varepsilon$.
- 2 [Boyd, '74]:** With Power Iteration, this ratio decreases.



Visual Representation of Power Iteration

- 1 Goal:** Find $\mathbf{x} \in \mathbb{R}_{>0}^n$ such that $\max_i \Phi(\mathbf{x})_i / \min_i \Phi(\mathbf{x})_i \leq 1 + \varepsilon$.
- 2 [Boyd, '74]:** With Power Iteration, this ratio decreases.
- 3 [Bhaskara and Vijayaraghavan, 2011]:** $\tilde{O}(n^3/\varepsilon)$ iterations suffice.



Power Iterations Downsides

Goal: Find $\mathbf{x} \in \mathbb{R}_{\geq 0}^n$ such that $\frac{\max_i \Phi(\mathbf{x})_i}{\min_i \Phi(\mathbf{x})_i} \leq 1 + \varepsilon$.

- Power Iteration converges exponentially fast on matrices that are well-conditioned.
- Sparse matrices are **ill-conditioned**.

Power Iterations Downsides

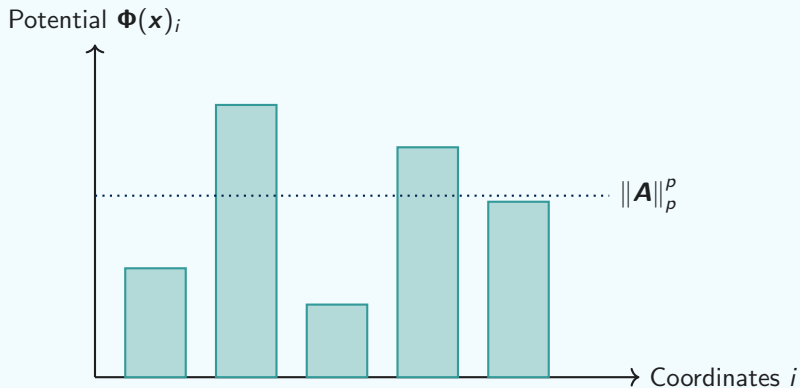
Goal: Find $\mathbf{x} \in \mathbb{R}_{\geq 0}^n$ such that $\frac{\max_i \Phi(\mathbf{x})_i}{\min_i \Phi(\mathbf{x})_i} \leq 1 + \varepsilon$.

- Power Iteration converges exponentially fast on matrices that are well-conditioned.
- Sparse matrices are **ill-conditioned**.

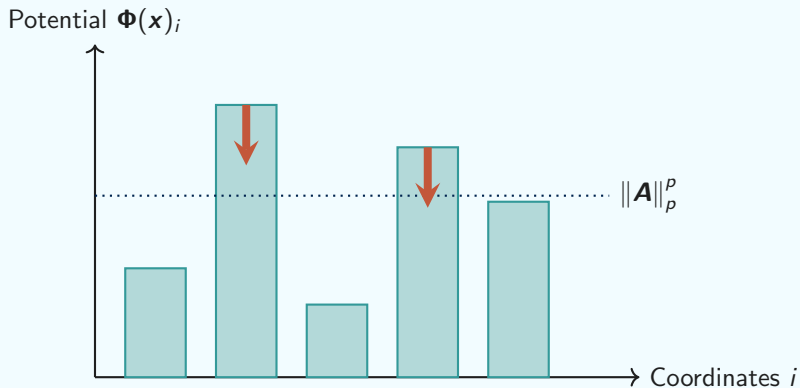
Somehow:

- We want to develop a method that does not require any conditioning on \mathbf{A} .
- Use potential $\Phi(\mathbf{x}) \approx \text{gradient} + \|\mathbf{A}\|_p^p$

Intuition of the New Algorithm



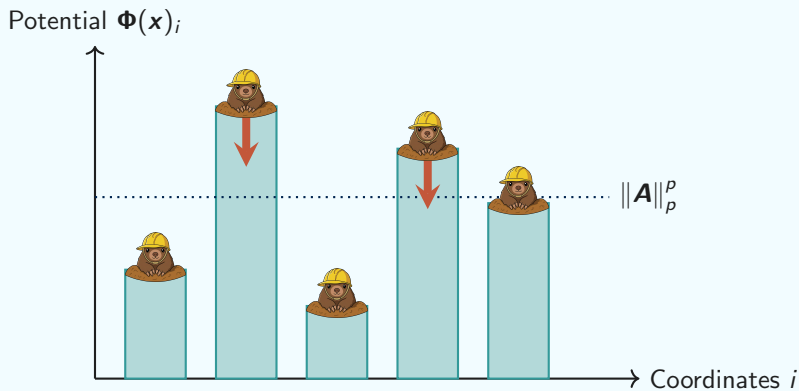
Intuition of the New Algorithm



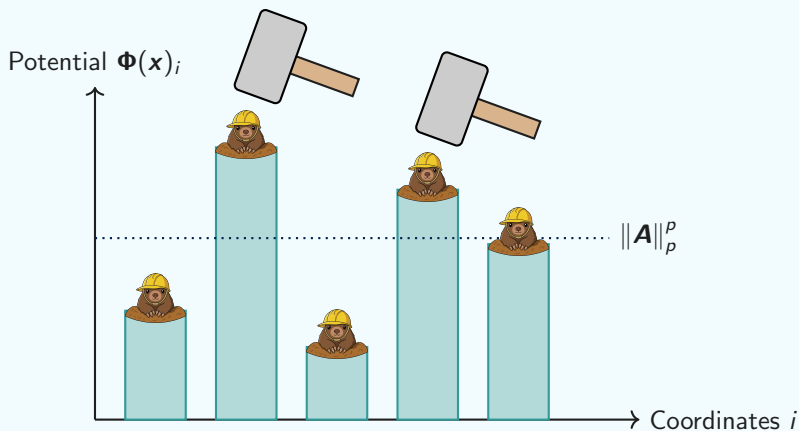
First Idea: Whac-A-Mole



Intuition of the Whac-A-Mole Algorithm



Intuition of the Whac-A-Mole Algorithm



Formalizing the Hammer

Coordinate-Scaling (i.e. the Hammer)

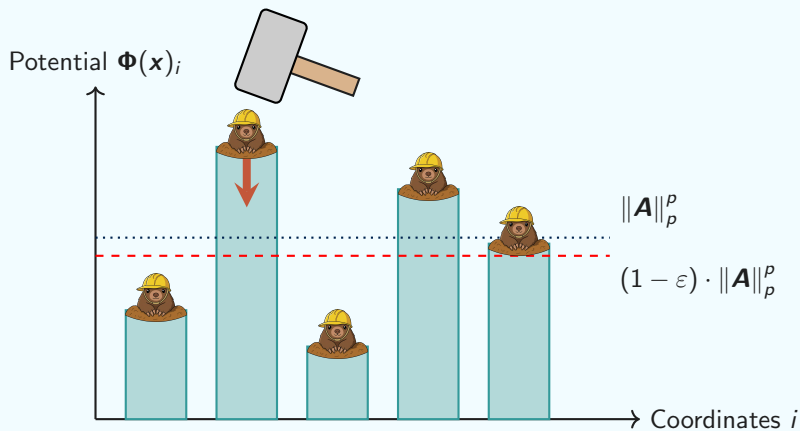
For some $\alpha > 0$, and a set $I \subseteq [n]$:

$$\mathbf{x}'_i = \begin{cases} (1 + \alpha) \cdot \mathbf{x}_i & \text{if } i \in I; \\ \mathbf{x}_i & \text{otherwise.} \end{cases}$$

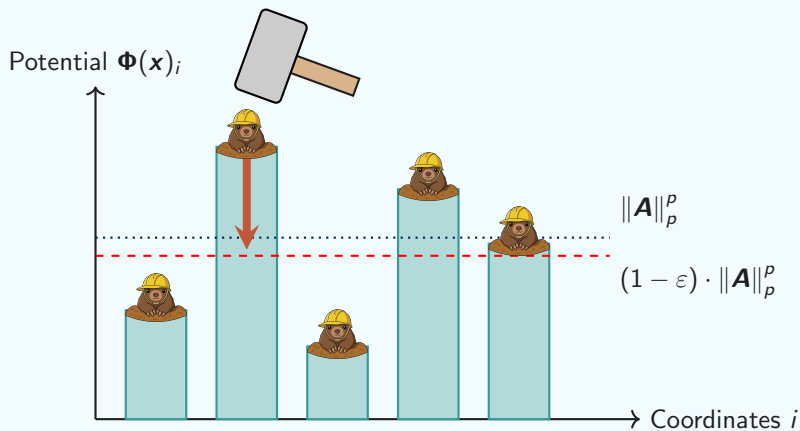
The Hammer

The value α controls the extent to which each entry of the potential vector varies between iterations.

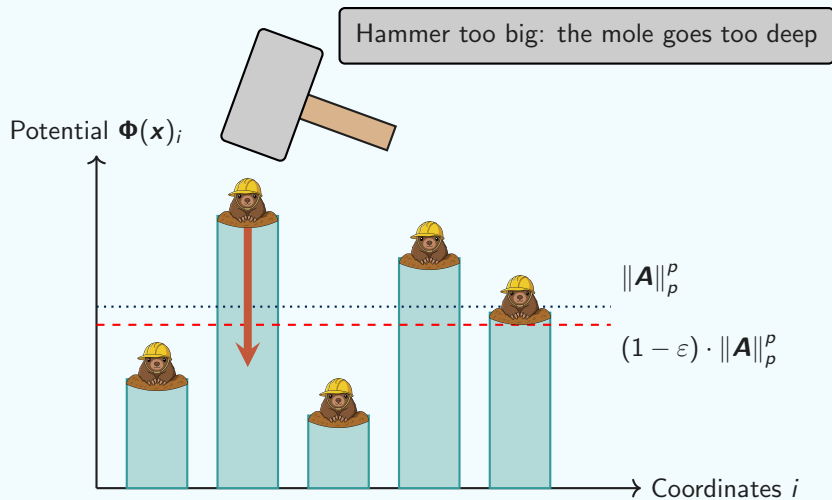
Calibrating the Hammer



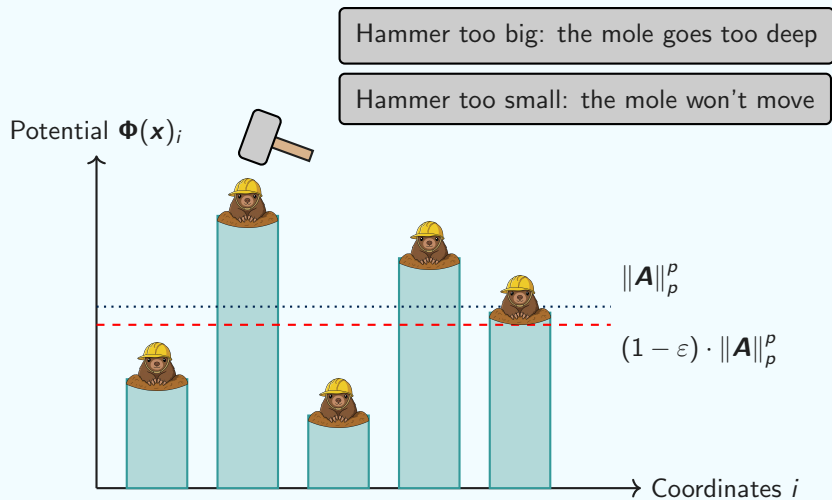
Calibrating the Hammer



Calibrating the Hammer



Calibrating the Hammer



Main Theorem

Theorem

If:

- The Hammer is **calibrated**.
- The Hammer **hits moles with large potential**.

Then:

- One mole being hit $\approx \varepsilon^{-1}$ times shows convergence.

Rules of the Game

Rules

- We are only allowed to hit moles with **potential larger than** $\|\mathbf{A}\|_p^p$.
- Once there is **a mole** that is hit $\approx \varepsilon^{-1}$ times, we win !

Problems

- Is there always a mole with potential larger than $\|\mathbf{A}\|_p^p$?

Rules of the Game

Rules

- We are only allowed to hit moles with **potential larger than** $\|\mathbf{A}\|_p^p$.
- Once there is a **mole** that is hit $\approx \varepsilon^{-1}$ times, we win !

Problems

- Is there always a mole with potential larger than $\|\mathbf{A}\|_p^p$?
 - Yes ! The potentials **sandwich** $\|\mathbf{A}\|_p^p$.

First strategy: Hit the mole with the largest potential.

First Try: The Width-Dependent Trap

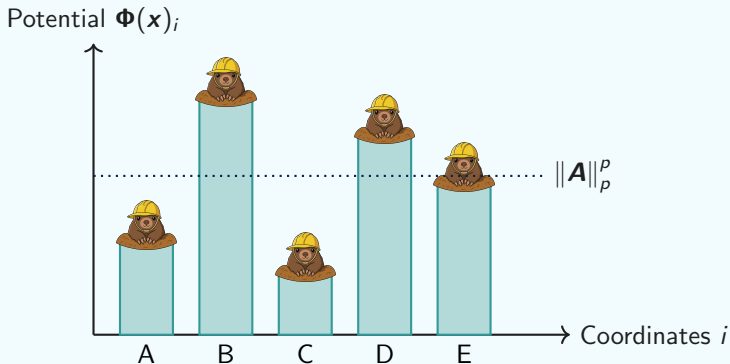
History

Mole	A	B	C	D	E
#Hit	0	0	0	0	0

Running time

End: One mole is hit ε^{-1} times.

Strategy: Hit the highest!



First Try: The Width-Dependent Trap

History

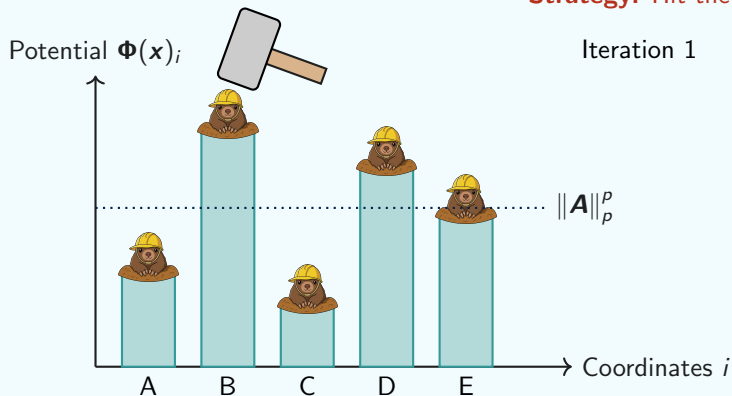
Mole	A	B	C	D	E
#Hit	0	1	0	0	0

Running time

End: One mole is hit ε^{-1} times.

Strategy: Hit the highest!

Iteration 1



First Try: The Width-Dependent Trap

History

Mole	A	B	C	D	E
#Hit	0	1	0	1	0

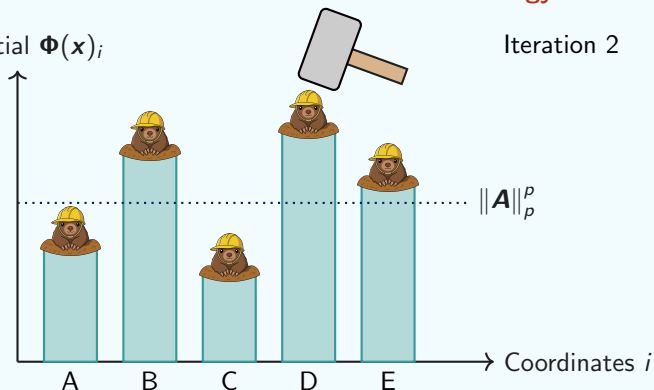
Running time

End: One mole is hit ε^{-1} times.

Strategy: Hit the highest!

Iteration 2

Potential $\Phi(x)_i$



First Try: The Width-Dependent Trap

History

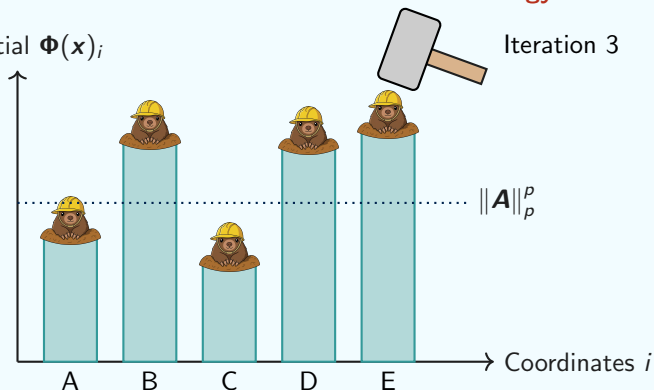
Mole	A	B	C	D	E
#Hit	0	1	0	1	1

Running time

End: One mole is hit ε^{-1} times.

Strategy: Hit the highest!

Potential $\Phi(x)_i$



First Try: The Width-Dependent Trap

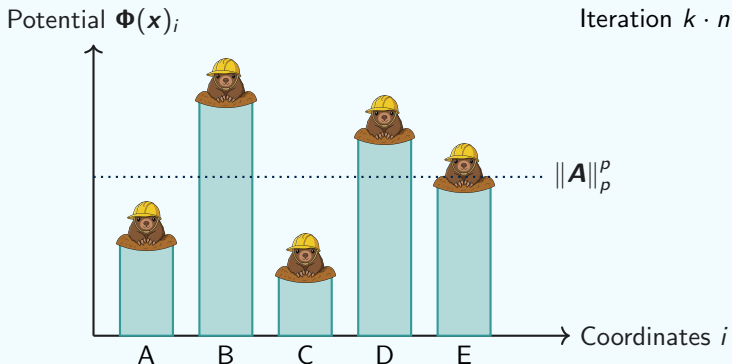
History

Mole	A	B	C	D	E
#Hit	k	k	k	k	k

Running time

End: One mole is hit ε^{-1} times.
After $k \cdot n$ iterations, one mole is hit k times.

Strategy: Hit the highest!



First Try: The Width-Dependent Trap

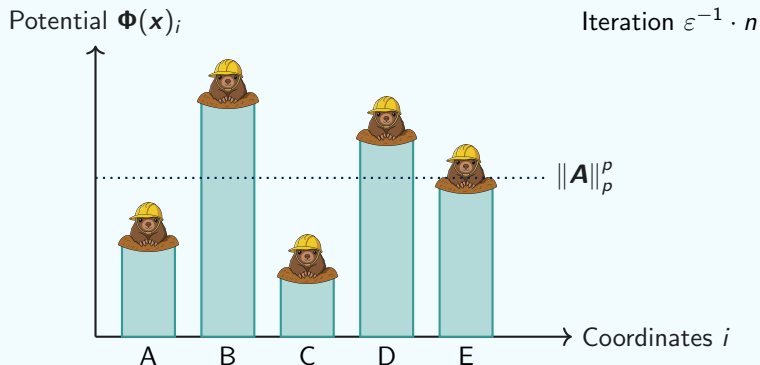
History

Mole	A	B	C	D	E
#Hit	$\frac{1}{\varepsilon}$	$\frac{1}{\varepsilon}$	$\frac{1}{\varepsilon}$	$\frac{1}{\varepsilon}$	$\frac{1}{\varepsilon}$

Running time

End: One mole is hit ε^{-1} times.
After $\frac{n}{\varepsilon}$ iterations, one mole is hit $\frac{1}{\varepsilon}$ times.

Strategy: Hit the highest!



First Try: The Width-Dependent Trap

Running Time

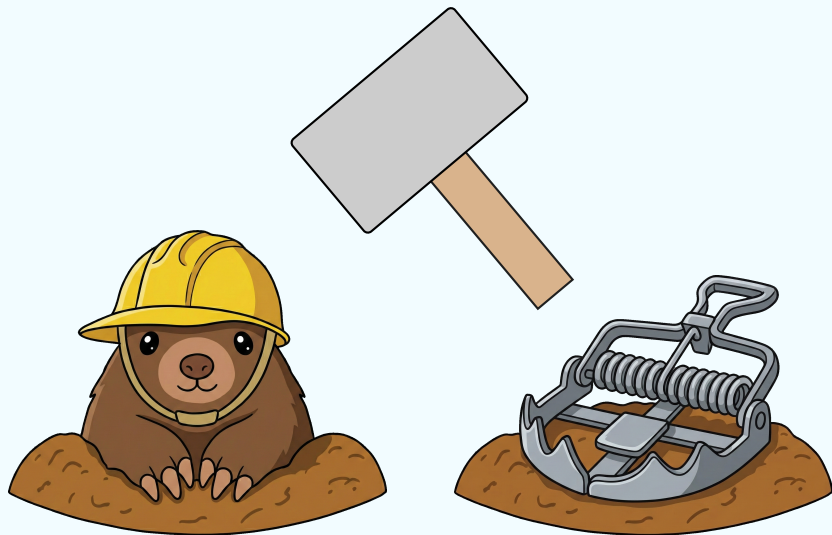
Convergence after $\tilde{O}\left(\frac{n}{\varepsilon}\right)$ iterations.

- Faster than power iteration.
- Not *width-independent* (i.e. dependency on n).

Solution

- We want to ensure the **same mole is hit** at each iteration.
- We will **trap moles** with potential slightly smaller than $\|\mathbf{A}\|_p^p$.

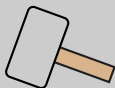
Second Idea: Whac-A-Mole + Trap the Moles



Second Try: One Slide Proof



A mole without large potential will never have large potential.



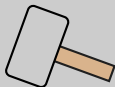
At each iteration, moles with large potential are hit.

Properties At each iteration, at least
of $\Phi(x)$ one mole has large potential.

Second Try: One Slide Proof



A mole without large potential will never have large potential.

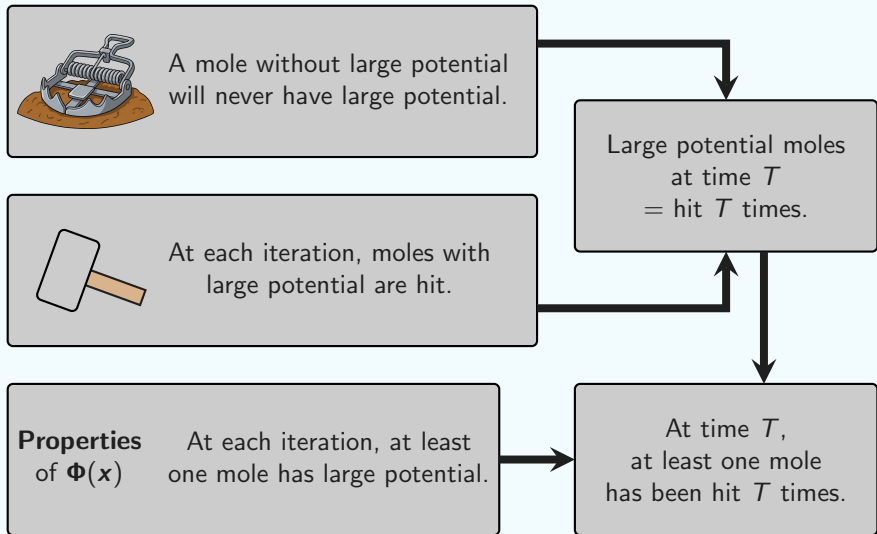


At each iteration, moles with large potential are hit.

Properties of $\Phi(\mathbf{x})$ At each iteration, at least one mole has large potential.

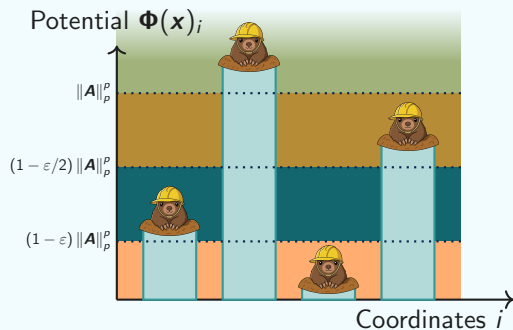
Large potential moles at time T
= hit T times.

Second Try: One Slide Proof



Second Try: Trap the Moles

Objective: No new moles in green.



High Potential

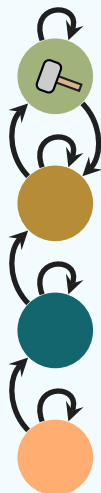
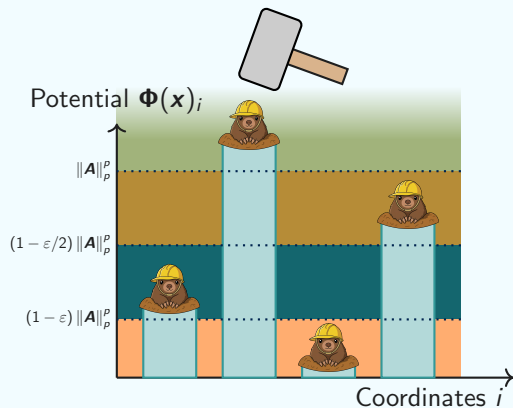


Low Potential

Second Try: Trap the Moles

Objective: No new moles in green.

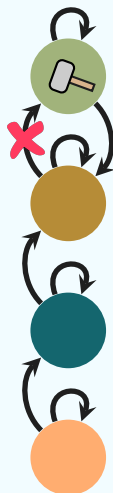
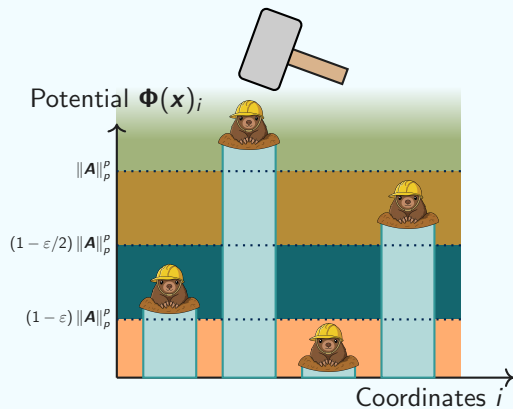
- Hit moles in green.



Second Try: Trap the Moles

Objective: No new moles in green.

- Hit moles in green.



High Potential

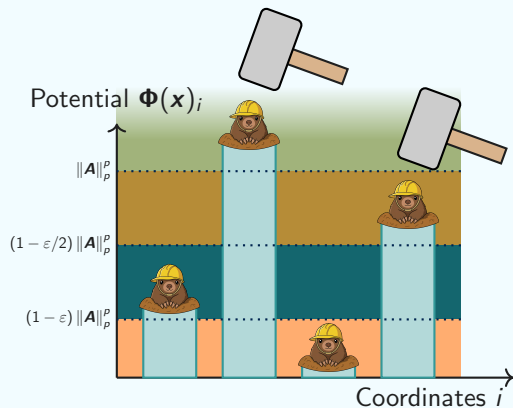


Low Potential

Second Try: Trap the Moles

Objective: No new moles in green.

- Hit moles in green.
- Hit moles in brown.



High Potential

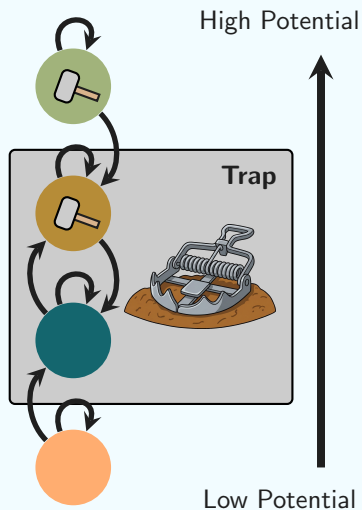
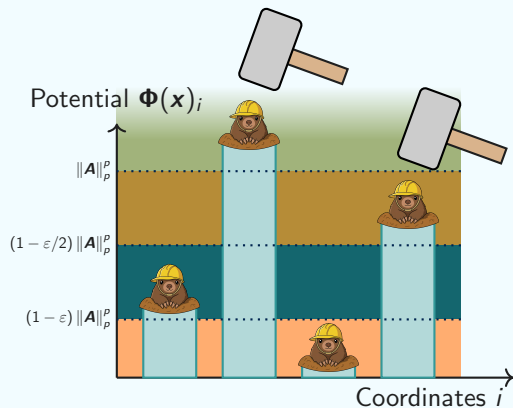


Low Potential

Second Try: Trap the Moles

Objective: No new moles in green.

- Hit moles in green.
- Hit moles in brown.



Second Try: Running Time and Remarks

Running Time

- Convergence after $\tilde{O}(\frac{1}{\varepsilon})$ iterations.
- Each iteration requires computing the potentials, hence each iteration runs in $\text{NNZ}(\mathbf{A})$.

Second Try: Running Time and Remarks

Running Time

- Convergence after $\tilde{O}(\frac{1}{\varepsilon})$ iterations.
- Each iteration requires computing the potentials, hence each iteration runs in $\text{NNZ}(\mathbf{A})$.

Remarks

- **Knowledge of $\|\mathbf{A}\|_p$:** Same algorithm with a guess and binary search.
- **Tall inputs:** Precondition the algorithm with Lewis weight sampling.

Conclusion

Main Elements

- $\tilde{O}\left(\frac{\text{NNZ}(\mathbf{A})}{q\varepsilon}\right)$ time algorithm to find a $1 - \varepsilon$ approximation to $\|\mathbf{A}\|_{q \rightarrow p}$ when \mathbf{A} has non-negative entries, $q \geq p \geq 1$.
- Assumptions correspond to instances where PTAS exists.

Conclusion

Main Elements

- $\tilde{O}\left(\frac{\text{NNZ}(\mathbf{A})}{q\varepsilon}\right)$ time algorithm to find a $1 - \varepsilon$ approximation to $\|\mathbf{A}\|_{q \rightarrow p}$ when \mathbf{A} has non-negative entries, $q \geq p \geq 1$.
- Assumptions correspond to instances where PTAS exists.

Future Works

- Use this algorithm to compute competitive tree-based linear oblivious routings in time $\tilde{O}(m^3)$?

Conclusion

Main Elements

- $\tilde{O}\left(\frac{\text{NNZ}(\mathbf{A})}{q\varepsilon}\right)$ time algorithm to find a $1 - \varepsilon$ approximation to $\|\mathbf{A}\|_{q \rightarrow p}$ when \mathbf{A} has non-negative entries, $q \geq p \geq 1$.
- Assumptions correspond to instances where PTAS exists.

Future Works

- Use this algorithm to compute competitive tree-based linear oblivious routings in time $\tilde{O}(m^3)$?
- Generalize the method to approximate other operator norms ?
- Hardness when $p > q > 1$?

Conclusion

Main Elements

- $\tilde{O}\left(\frac{\text{NNZ}(\mathbf{A})}{q\varepsilon}\right)$ time algorithm to find a $1 - \varepsilon$ approximation to $\|\mathbf{A}\|_{q \rightarrow p}$ when \mathbf{A} has non-negative entries, $q \geq p \geq 1$.
- Assumptions correspond to instances where PTAS exists.

Future Works

- Use this algorithm to compute competitive tree-based linear oblivious routings in time $\tilde{O}(m^3)$?
- Generalize the method to approximate other operator norms ?
- Hardness when $p > q > 1$?

My website



Thank You !